

Statistical inference for discretely observed stochastic differential equations with mixed effects

Catherine Larédo (1)

Joint work with Maud Delattre (2) & Valentine Genon-Catalot (3)

(1) Laboratoire MalAGE, I.N.R.A. and LPMA, Université Denis Diderot, CNRS-UMR 7599,

(2) AgroParisTech, France ,

(3) UMR CNRS 8145, Laboratoire MAP5, Université Paris Descartes, Sorbonne Paris Cité

SAPS XI, July 17-21 2017, Peterhof, Russia

Based on two papers : Delattre, Genon-Catalot & Larédo, 2017 (a),(b)

Mixed effects models

- Longitudinal data widely collected in clinical trials, epidemiology, pharmacokinetic pharmacodynamics experiments on N individuals.
- Interest may focus on population effects among individuals and on individual specific behaviour.
- Random effects \Rightarrow accomodate among inter-individual variability.
- while the same structural model rules the individual dynamics.
- Structural model here: Stochastic Differential Equations \Rightarrow SDE with mixed effects (SDEME).

Main issue for general mixed effects models

- Estimation of parameters in the distribution of random effects.
- Difficult in practice due to the intractable likelihood function.
- Development of computationally intensive numerical methods.
- Large computation times due to iterative settings.

Diffusion process with mixed effects

$$\begin{cases} dX(t) = b(X(t), \Phi)dt + \sigma(X(t), \Psi)dW(t), \\ X(0) = x, \\ x \in \mathbb{R}, t \in [0, T]. \end{cases} \quad (1)$$

Φ, Ψ random variables, independent of $W(\cdot)$,

$W(\cdot)$: Wiener process.

AIM: Estimation of unknown parameters in the distribution of Φ, Ψ .

MIXED EFFECTS: Presence of both fixed effects and random effects.

Remark: Classical problem if $\Phi = \varphi, \Psi = \psi$ are non random, $T \rightarrow \infty$.

- ★ Continuous observations: Kutoyants (1984), Lipster & Shiryaev (2001)
- ★ Discrete observations: estimation of (φ, ψ) : e.g. Kessler(1997).

Repeated observations of discretized processes

Discrete observations on $[0, T]$ of N *i.i.d.* processes $(X_i(t))$

$$\begin{cases} dX_i(t) = b(X_i(t), \Phi_i)dt + \sigma(X_i(t), \Psi_i)dW_i(t), \\ X_i(0) = x, \\ x \in \mathbb{R}, t \in [0, T], i = 1, \dots, N, \end{cases}$$

- $(\Phi_i, \Psi_i), i = 1, \dots, N$: *i.i.d.* random variables.
- $W_i, i = 1, \dots, N$: independent Wiener processes.
- $((\Phi_i, \Psi_i), i = 1, \dots, N)$ and $W_i, i = 1, \dots, N$ independent.

Observations ($N \rightarrow \infty$ and $n \rightarrow \infty$)

Processes observed at times $t_j = jT/n, j = 1, \dots, n$; T fixed.

Observations: $(X_{i,n} := (X_i(t_j), j = 1, \dots, n), i = 1, \dots, N)$.

Notation: $\Delta = \Delta_n = T/n$ ($n \rightarrow \infty \Rightarrow \Delta_n \rightarrow 0$).

Main issues for SDEME

Likelihood for SDEME

- As for general mixed models: **intractable** likelihood.
- Additional pb: Discrete observations of each SDE on $[0, T]$.

Two possible sources of randomness in the structural SDE

- Random effects in the drift and/or in the diffusion coef.
- Natural to incorporate in the SDE model a joint distribution.
- Discrete observations of SDE : Different rates of convergence for estimating φ and ψ (Kessler, 1997).
- Important issue: understanding how estimation performs in SDEME.
- Necessary to clarify what to expect from numerical methods.

AIM

Investigate the statistical properties of estimators according to N , nb of individuals and n , nb of observations per individual.

Likelihood for SDE with mixed effects

Parametric distribution for the $(\Phi_i, \Psi_i) := \nu_{\vartheta}(d\varphi, d\psi)$

Likelihood of the sample $(X_{i,n}, i = 1, \dots, N)$:

$$L_{N,n}(\vartheta) = \prod_{i=1}^N L_n(X_{i,n}, \vartheta), \quad \text{where}$$

$$L_n(X_{i,n}, \vartheta) = \int L_n(X_{i,n}, \varphi, \psi) \nu_{\vartheta}(d\varphi, d\psi) \quad : \text{Likelihood of } X_{i,n}, \quad (2)$$

$$L_n(X_{i,n}, \varphi, \psi) \quad : \text{Conditional likelihood given } \Phi_i = \varphi, \Psi_i = \psi \quad (3)$$

i.e. likelihood of $dX_i^{\varphi, \psi}(t) = b(X_i^{\varphi, \psi}(t), \varphi)dt + \sigma(X_i^{\varphi, \psi}(t), \psi) dW_i(t)$.

Two main difficulties

(1) Discrete observations: intractable $L_n(X_{i,n}, \varphi, \psi) \Rightarrow$ **Approximation**.

(2) Integration in (2) : no closed form for most distributions ν_{ϑ}

\Rightarrow **Choice of specific models $b(., .), \sigma(., .)$ and distributions $\nu_{\vartheta}(., .)$.**

Specific distribution for the random effects

- ★ $\mathcal{L}_n(X_{i,n}, \vartheta)$: approximation of $L_n(X_{i,n}, \vartheta)$ for the i -th path.
- ★ $\psi = \gamma^{-1/2} \Rightarrow \{\vartheta = (\gamma, \varphi) \text{ and } \nu_{\vartheta}(d\gamma, d\varphi)\}$.

$$\mathcal{L}_n(X_{i,n}, \vartheta) = \int_{(0,+\infty) \times \mathbb{R}^d} \mathcal{L}_n(X_{i,n}, \gamma, \varphi) \nu_{\vartheta}(d\gamma, d\varphi). \quad (4)$$

FOCUS: Distributions of the random effects such that the integration of (4) is explicit.

Three cases of mixed effects

- 1 $\Psi_i = \psi = \gamma^{-1/2}$ unknown and $\Phi_i \sim \mathcal{N}_d(\mu, \gamma^{-1}\Omega) \Rightarrow \theta = (\gamma, \mu, \Omega)$
- 2 $\Phi_i = \phi$ unknown ; $\Psi_i = \Gamma_i^{-1/2}$ with $\Gamma_i \sim G(a, \lambda) \Rightarrow \tau = (\lambda, a, \phi)$.
- 3 Joint distribution for (Φ_i, Ψ_i) : $\Psi_i = \Gamma_i^{-1/2}$, $\Gamma_i \sim G(a, \lambda)$. and given $\Gamma_i = \gamma$, $\Phi_i \sim \mathcal{N}_d(\mu, \gamma^{-1}\Omega) \Rightarrow \vartheta = (\lambda, a, \mu, \Omega)$

Detail here: Cases (1) and (3).

Case of a joint distribution for the random effects

- Joint distribution for (Φ_i, Ψ_i) : $\Psi_i = \Gamma_i^{-1/2}$, $\Gamma_i \sim G(a, \lambda)$. and given $\Gamma_i = \gamma$, $\Phi_i \sim \mathcal{N}_d(\boldsymbol{\mu}, \gamma^{-1}\boldsymbol{\Omega})$.
- Model where the marginal distribution of Φ_i is not Gaussian
 $\Phi_i - \boldsymbol{\mu}$ has a Student distribution

Construction of two distinct approximate likelihoods (a), (b)

- (a) Derived from the study of Case (1)
- (b) Separation of the inference for (a, λ) and $(\boldsymbol{\mu}, \boldsymbol{\Omega})$

- (a) Good approximation of the likelihood.
- (b) Easier to implement.

Approximate conditional likelihood (1)

Specific model : Linear mixed effects

- $b(x, \varphi) = \varphi' b(x)$ with $\varphi' = (\varphi_1, \dots, \varphi_d)$; $\sigma(x, \psi) = \psi \sigma(x)$;
- $b(.) = (b_1(.), \dots, b_d(.))'$ and $\sigma(.)$ known ; x known.

Approximate conditional likelihood

Derived from **Euler scheme** $(Y_{i,n})$ of $(X_i^{\varphi, \psi})$ with $\Delta = T/n$,

$$dX_i^{\varphi, \psi}(t) = \varphi b(X_i^{\varphi, \psi}(t))dt + \psi \sigma(X_i^{\varphi, \psi}(t)) dW_i(t), \quad X_i^{\varphi, \psi}(0) = x$$

Exact $L_n(X_{i,n}, \varphi, \psi)$ replaced by \mathcal{L}_n , likelihood of $(Y_{i,n})$:

$$Y_{i,j} - Y_{i,j-1} = \Delta \varphi' b(Y_{i,j-1}) + \sqrt{\Delta} \psi \sigma(Y_{i,j-1}) \epsilon_{i,j},$$

with $Y_{i,0} = x$ and $\epsilon_{i,j} = \frac{W_i(t_j) - W_i(t_{j-1})}{\sqrt{\Delta}}$ i.i.d. $\mathcal{N}(0, 1)$.

Approximate conditional likelihood given $\Phi_i = \varphi, \Psi_i = \psi$

Set $\Psi_i = \psi = \gamma^{-1/2}$:

$$\mathcal{L}_n(X_{i,n}, \gamma, \varphi) = \gamma^{n/2} \exp \left[-\frac{\gamma}{2} (S_{i,n} + \varphi' V_{i,n} \varphi - 2\varphi' U_{i,n}) \right], \quad \text{where}$$

$$S_{i,n} = S_i = \frac{1}{\Delta} \sum_{j=1}^n \frac{(X_i(t_j) - X_i(t_{j-1}))^2}{\sigma^2(X_i(t_{j-1}))},$$

$$V_{i,n} = V_i = \left(\sum_{j=1}^n \Delta \frac{b_k(X_i(t_{j-1})) b_\ell(X_i(t_{j-1}))}{\sigma^2(X_i(t_{j-1}))} \right)_{1 \leq k, \ell \leq d},$$

$$U_{i,n} = U_i = \left(\sum_{j=1}^n \frac{b_k(X_i(t_{j-1}))(X_i(t_j) - X_i(t_{j-1}))}{\sigma^2(X_i(t_{j-1}))} \right)_{1 \leq k \leq d},$$

Preliminary discretization results

Three Sufficient statistics

Discretization results: As $n \rightarrow \infty$

$$\frac{S_{i,n}}{n} \rightarrow \Psi_i^2 = \Gamma_i^{-1} \quad \text{in prob. (quadratic variations),}$$

$$V_{i,n} \rightarrow V_i(T) = \left(\int_0^T \frac{b_k(X_i(t))b_l(X_i(t))}{\sigma^2(X_i(t))} dt \right)_{1 \leq k, l \leq d} \quad \text{a.s. (Riemann),}$$

$$U_{i,n} \rightarrow U_i(T) = \left(\int_0^T \frac{b_k(X_i(t))}{\sigma^2(X_i(t))} dX_i(t) \right)_{1 \leq k \leq d} \quad \text{in prob. (stoch. integral)}$$

Assumptions for the statistical study

(H1): Assume that $b(\cdot), \sigma(\cdot)$ C^2 bounded; $\sigma(\cdot) \geq \sigma_0 > 0$.

(H2) $V_i(T)$ positive definite a.s.

Results of Case (1): $\Psi_i = \psi$ fixed unknown

$$\begin{aligned}dX_i(t) &= \Phi_i' b(X_i(t))dt + \Psi_i \sigma(X_i(t))dW_i(t), \\X_i(0) &= x \in \mathbb{R}, \quad t \in [0, T], \quad T = n\Delta; \quad i = 1, \dots, N.\end{aligned}$$

$\Psi_i = \psi = \gamma^{-1/2}$ unknown and $\Phi_i \sim \mathcal{N}_d(\mu, \gamma^{-1}\Omega) \Rightarrow \theta = (\gamma, \mu, \Omega)$

Proposition: Explicit approximate likelihood for $(X_{i,n})$

$$\begin{aligned}\mathcal{L}_n(X_{i,n}, \theta) &= \gamma^{n/2} (\det(I_d + V_{i,n} \Omega))^{-1/2} \exp -\frac{\gamma}{2} (S_{i,n} + T_{i,n}(\mu, \Omega)), \\T_{i,n}(\mu, \Omega) &= (\mu - V_{i,n}^{-1} U_{i,n})' R_{i,n}^{-1} (\mu - V_{i,n}^{-1} U_{i,n}) - U_{i,n}' V_{i,n}^{-1} U_{i,n} \\R_{i,n} &= V_{i,n}^{-1} + \Omega.\end{aligned}$$

- ★ Formula $\mathcal{L}_n(X_{i,n}, \theta)$ holds if Ω is singular.
- ★ Possibility to have both fixed and random effects in the drift coefficient.

Asymptotic properties of estimators

- $L_{N,n}(\theta) = \prod_{i=1}^N \mathcal{L}_n(X_{i,n}, \theta) \Rightarrow \ell_{N,n}(\theta) = \log L_{N,n}(\theta)$ (loglikelihood)
- Define estimators $\tilde{\theta}_{N,n}$ maximizing $\ell_{N,n}(\theta)$.
- Different rates of convergence for γ and μ, Ω .

$$D_{N,n} = \begin{pmatrix} \frac{1}{\sqrt{Nn}} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \frac{1}{\sqrt{N}} I_d & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \frac{1}{\sqrt{N}} I_{d \times d} \end{pmatrix}, \quad \mathcal{I}(\theta) = \left(\begin{array}{c|c} \frac{1}{2\gamma^2} & \mathbf{0} \\ \hline \mathbf{0} & I(\theta) \end{array} \right), \quad (5)$$

$I(\theta)$ explicit covariance matrix.

Theorem

Assume (H1)-(H2), $I(\theta)$ invertible. If $N, n \rightarrow \infty$, $N/n \rightarrow 0$, there exists a solution $\tilde{\theta}_{N,n}$ with prob. tending to 1 which is consistent and s.t.

$$D_{N,n}^{-1}(\tilde{\theta}_{N,n} - \theta) \rightarrow_{\mathcal{D}} \mathcal{N}_q(0, \mathcal{I}^{-1}(\theta)) \text{ under } \mathbb{P}_\theta,$$

$$(q = 1 + d + d(d+1)/2.)$$

Comments

- ① Theorem holds if Ω singular:
Possible to include **mixed effects in the drift coefficient**.
- ② Constraint $N/n \rightarrow 0$
- ③ Fixed and random effects in the drift: **Same rates of convergence**.
- ④ **No loss of information from the discrete observations:**
Continuous observations $(X_i(t), i = 1, \dots, N)$ (γ known, $d = 1$):
Delattre et al.(2013): M.L.E $\hat{\theta}_{N,n}$ strongly consistent and same asymptotic variance for $\hat{\theta}_{N,n}$ and $\tilde{\theta}_{N,n}$.
- ⑤ **Loss of efficiency w.r.t. direct observations** of $\Phi_i \sim \mathcal{N}_2(\mu, \gamma^{-1}\omega^2)$

Joint distribution for random effects (Φ_i, Ψ_i)

Assumption: (Φ_i, Ψ_i) are dependent.

$$\Psi_i = \frac{1}{\Gamma_i^{1/2}}, \quad \Gamma_i \sim G(a, \lambda), \text{ and given } \Gamma_i = \gamma, \quad \Phi_i \sim \mathcal{N}_d(\mu, \gamma^{-1}\Omega).$$

Construction of two distinct approximate likelihoods (1), (2)

- (1) Derived from the study of Case (1).
- (2) Separation of the inference for (a, λ) and (μ, Ω) .

- (1) Good approximation of the likelihood.
- (2) Easier to implement.

Remark: Φ_i has a non Gaussian marginal distribution ($\Phi_i - \mu \sim \text{Student}$).

Approximate likelihood for one path

$$\vartheta = (\lambda, a, \boldsymbol{\mu}, \boldsymbol{\Omega})$$

$$\Lambda_n(X_{i,n}, \vartheta) = \int_0^{+\infty} \mathcal{L}_n(X_{i,n}, \gamma, \boldsymbol{\mu}, \boldsymbol{\Omega}) \gamma^{a-1} \exp(-\lambda\gamma) \frac{\lambda^a}{\Gamma(a)} d\gamma, \quad (6)$$

where $\mathcal{L}_n(X_{i,n}, \gamma, \boldsymbol{\mu}, \boldsymbol{\Omega})$ likelihood obtained for fixed γ :

$$\begin{aligned} \mathcal{L}_n(X_{i,n}, \gamma, \boldsymbol{\mu}, \boldsymbol{\Omega}) &= \gamma^{n/2} (\det(\mathbf{I}_d + V_{i,n} \boldsymbol{\Omega}))^{-1/2} \exp -\frac{\gamma}{2} (S_{i,n} + T_{i,n}(\boldsymbol{\mu}, \boldsymbol{\Omega})) \\ T_{i,n}(\boldsymbol{\mu}, \boldsymbol{\Omega}) &= (\boldsymbol{\mu} - V_{i,n}^{-1} U_{i,n})' R_{i,n}^{-1} (\boldsymbol{\mu} - V_{i,n}^{-1} U_{i,n}) - U_{i,n}' V_{i,n}^{-1} U_{i,n}. \end{aligned}$$

Difficulty: (6) requires $2\lambda + S_{i,n} + T_{i,n}(\boldsymbol{\mu}, \boldsymbol{\Omega}) > 0$.

Need to define the random sets:

$$E_{i,n}(\vartheta) = \{S_{i,n} + T_{i,n}(\boldsymbol{\mu}, \boldsymbol{\Omega}) > 0\} \ ; \ E_{N,n}(\vartheta) = \cap_{i=1}^N E_{i,n}(\vartheta).$$

Method 1 for estimating $\vartheta = (\lambda, a, \mu, \Omega)$

Explicit approximate likelihood

$$\text{On } E_{N,n}(\vartheta), \quad \Lambda_{N,n}(\vartheta) = \prod_{i=1}^N \Lambda_n(X_{i,n}, \vartheta), \quad \text{where} \quad (7)$$

$$\Lambda_n(X_{i,n}, \vartheta) = \frac{\lambda^a \Gamma(a + (n/2))}{\Gamma(a) \left(\lambda + \frac{S_{i,n}}{2} + \frac{T_{i,n}(\mu, \Omega)}{2} \right)^{a+(n/2)}} \frac{1}{(\det(I_d + V_{i,n}\Omega))^{1/2}} \quad (8)$$

Problem: Find a sufficient. condition ensuring $\forall \theta_0, \theta, \mathbb{P}_{\vartheta_0}(E_{N,n}(\vartheta)) \rightarrow 1$.

Proposition: If $a > 4$, there exists a subset $F_{N,n}$ containing $E_{N,n}(\vartheta)$ satisfying $P_{\vartheta_0}(F_{N,n}) \rightarrow 1$ as $N, n \rightarrow \infty$.

Formula (8) holds for non invertible $\Omega \Rightarrow$ Mixed effects for Φ .

Simplifying the likelihood: Method 2

For large n , using $S_{i,n}/n \rightarrow \Gamma_i^{-1}$

$$\log \Lambda_n(X_{i,n}, \vartheta) \simeq \mathbf{V}_n^{(1)}(X_{i,n}, \lambda, a) + \mathbf{V}_n^{(2)}(X_{i,n}, \boldsymbol{\mu}, \boldsymbol{\Omega}),$$

$$\mathbf{V}_n^{(1)}(X_{i,n}, \lambda, a) = \log \left(\frac{\lambda^a \Gamma(a + (n/2))}{\Gamma(a) (\lambda + \frac{S_{i,n}}{2})^{a+(n/2)}} \right)$$

$$\mathbf{V}_n^{(2)}(X_{i,n}, \boldsymbol{\mu}, \boldsymbol{\Omega}) = -\frac{n}{2S_{i,n}} T_{i,n}(\boldsymbol{\mu}, \boldsymbol{\Omega}) - \frac{1}{2} \log(\det(I_d + V_{i,n}\boldsymbol{\Omega}))$$

$\mathbf{V}_n^{(1)}(X_{i,n}, \lambda, a)$: appr. likelihood for $b \equiv 0$ (Delattre et al., 2015).

New approximate loglikelihood for the i th path

$$\mathbf{V}_n(X_{i,n}, \vartheta) = \mathbf{V}_n^{(1)}(X_{i,n}, \lambda, a) + \mathbf{V}_n^{(2)}((X_{i,n}, \boldsymbol{\mu}, \boldsymbol{\Omega})) \quad (9)$$

Interest of \mathbf{V}_n : estimation of (λ, a) and $(\boldsymbol{\mu}, \boldsymbol{\Omega})$ performed separately.

Random effects in both coef.: estimating equations

- ★ Two different approximations of the loglikelihood:

$$\mathbf{U}_{N,n}(\vartheta) = \sum_{i=1}^N \log \Lambda_n(X_{i,n}, \vartheta), \quad \mathbf{V}_{N,n}(\vartheta) = \sum_{i=1}^N \mathbf{V}_n(X_{i,n}, \vartheta),$$

- ★ Two estimating equations leading to estimators:

$$\nabla_{\vartheta} \mathbf{U}_{N,n}(\tilde{\vartheta}_{N,n}) = 0, \quad \nabla_{\vartheta} \mathbf{V}_{N,n}(\bar{\vartheta}_{N,n}) = 0.$$

Random effects in both coef.: properties of estimators

The estimators $\tilde{\vartheta}_{N,n}$ and $\bar{\vartheta}_{N,n}$ of $\theta = (\lambda, a, \mu, \Omega)$ satisfy:

Theorem

Assume $a > 6$, $N/n \rightarrow 0$ and that $J(\vartheta)$ is invertible. Then, a solution $\tilde{\vartheta}_{N,n}$ exists with probability tending to 1 which is consistent and such that, under \mathbb{P}_{ϑ} ,

$$\sqrt{N}(\tilde{\vartheta}_{N,n} - \vartheta) \rightarrow_{\mathcal{D}} \mathcal{N}_q(0, \mathcal{J}^{-1}(\vartheta))$$

where $q = 2 + d + d(d+1)/2$. For the first two components of $\sqrt{N}(\tilde{\vartheta}_{N,n} - \vartheta)$, the constraint N/n^2 is enough.

The same properties hold for $\bar{\vartheta}_{N,n}$. These two estimators are asymptotically equivalent.

$$\star E_{\vartheta}(\Gamma_i^{-1}) = \lambda/(a-1).$$

$\star a > 6$: moment property for Γ_i^{-1} (i.e. quadratic variations of $X_i(t)$).

$\mathcal{J}(\vartheta)$ block diagonal matrix precised in the next slide.

Random effects in both coef.: Covariance matrix

$$\mathcal{J}(\vartheta) = \left(\begin{array}{c|c} l_0(\lambda, a) & \mathbf{0} \\ \hline \mathbf{0} & J(\vartheta) \end{array} \right), \quad l_0(\lambda, a) = \begin{pmatrix} \frac{a}{\lambda^2} & -\frac{1}{\lambda} \\ -\frac{1}{\lambda} & \psi'(a) \end{pmatrix},$$

$J(\vartheta)$ is explicit (depends on $\Gamma_i, U_i(T), V_i(T)$).

$l_0(\lambda, a)$: Fisher information matrix for direct observations $\Gamma(a, \lambda)$.

$\Psi(a)$ Digamma function

Comments

- ① Random effects in the drift or/and in the diffusion coefficient:
Same rates of convergence \sqrt{N} .
- ② Estimation of (λ, a) : no loss of efficiency w.r.t. direct observations of N i.i.d. Γ_i and weaker constraint $N/n^2 \rightarrow 0$
- ③ $a > 6$: moment condition on Γ_i^{-1} ($\mathbb{E}_\vartheta \Gamma_i^{-6} < +\infty$).
- ④ Note that the marginal distribution of Φ_i is not Gaussian in this set-up.

Remark: Similar results for Case (2) :

Fixed effects in the drift and random effects in the diffusion coefficients.

Assessment on various examples

Joint distribution for (Φ_i, Γ_i) : $\Gamma_i \sim \Gamma(a, \lambda)$, $\Phi_i | \Gamma_i = \gamma \sim \mathcal{N}(\mu, \gamma^{-1}\Omega)$.

(1) Mixed effect Brownian motion:

$$dX_i(t) = \Phi_i dt + \Gamma_i^{-1} dW_i(t), X_i(0) = 0 .$$

(2) Mixed O.U process: $\Gamma_i = \gamma$ or $\Gamma_i \sim G(a, \lambda)$

$$dX_i(t) = (\rho - \Phi_i X_i(t))dt + \Gamma_i^{-1/2} dW_i(t), X_i(0) = 0 ,$$

(3) Mixed O.U. with two ind. random effects: $\Gamma_i = \gamma$ or $\Gamma_i \sim G(a, \lambda)$

$$dX_i(t) = (\Phi_{i,1} - \Phi_{i,2} X_i(t))dt + \Gamma_i^{-1/2} dW_i(t), X_i(0) = 0 ,$$

(4) Mixed C.I.R. process ($\rho > 0 \Rightarrow \forall t \geq 0, X_i(t) \geq 0$.)

$$dX_i(t) = (\rho X_i(t) - \Phi_i)dt + \Gamma_i^{-1/2} \sqrt{|X_i(t)|} dW_i(t), X_i(0) = x > 0 ,$$

(5) Implementation on a real data set of membrane potential paths

Simulation design and results

- Each SDE : 100 data sets with N subjects on $[0, T]$ with $T = 5$.
- Simulation: First draw the random effect.
- Exact simulation for Models 1-3 ; Alfonsi scheme for (4).
- Two sampling intervals $\Delta = 0.01; 0.005$.
- Two values for N : $N = 50, 100$.
- Preliminaries: standard estimation results from direct observations of N i.i.d. sample of (Φ_i, Γ_i)

Results

For Case 3 (joint distribution), similar results with Methods 1 and 2;
Method 2: easier to implement \Rightarrow Only Method 2 results presented.

Drift with random effect, fixed or random diff. coef.

$$dX_i(t) = \Phi_i dt + \gamma^{-1/2} dW_i(t); \Phi_i \sim \mathcal{N}(\mu, \gamma^{-1}\omega^2)$$

	value	$\Delta = 0.01$ ($n = 500$)	$\Delta = 0.005$ ($n = 1000$)
μ	0	0.01 (0.04)	0.01 (0.03)
ω^2	0.1	0.10 (0.06)	0.1 (0.04)
γ	4.00	4.01 (0.04)	4.00 (0.02)

$$dX_i(t) = \Phi_i dt + \Gamma_i^{-1/2} dW_i(t); \Gamma_i \sim G(a, \lambda)$$

	value	$\Delta = 0.025$ ($n = 200$)	$\Delta = 0.005$ ($n = 1000$)
μ	-0.50	- 0.49 (0.06)	- 0.51 (0.06)
ω^2	0.50	0.45 (0.11)	0.49 (0.12)
m	4.00	3.85 (0.22)	3.96 (0.23)
t	1.32	1.24 (0.06)	1.30 (0.06)

$$N = 50, T = 5; (a, \lambda) = (8, 2), m = a/\lambda, t = \psi(a) - \log \lambda; E(\Gamma_i^{-1}) = 2/7.$$

Drift with mixed effects, fixed or random diff. coef.

$$dX_i(t) = (\rho X_i(t) + \Phi_i)dt + \gamma^{-1/2}dW_i(t); \Phi_i \sim \mathcal{N}(\mu, \gamma^{-1}\omega^2);$$

	value	$\Delta = 0.01$ ($n = 500$)	$\Delta = 0.005$ ($n = 1000$)
ρ	-0.1	-0.11 (0.02)	-0.10 (0.01)
μ	1	1.01 (0.08)	1.02 (0.06)
ω^2	0.4	0.40 (0.14)	0.40 (0.12)
γ	4.00	4.01 (0.04)	4.01 (0.02)

$$dX_i(t) = (\rho - \Phi_i X_i(t))dt + \Gamma_i^{-1/2}dW_i(t); \Gamma_i \sim G(a, \lambda)$$

	value	$\Delta = 0.025$ ($n = 200$)	$\Delta = 0.005$ ($n = 1000$)
ρ	1.00	0.99 (0.07)	1.00 (0.08)
μ	0.50	0.49 (0.06)	0.50 (0.06)
ω^2	0.10	0.08 (0.04)	0.09 (0.04)
m	4.00	3.95 (0.21)	3.99 (0.21)
t	1.32	1.26 (0.05)	1.30 (0.05)

$$N = 50, T = 5; m = a/\lambda, t = \psi(a) - \log \lambda \quad (E(\Gamma_i^{-1}) = 2/7).$$

Drift with 2 random effects, fixed or random diff. coef.

$$dX_i(t) = (\Phi_{i,1}X_i(t) + \Phi_{i,2})dt + \gamma^{-1/2}dW_i(t)$$

	value	$\Delta = 0.01$ ($n = 500$)	$\Delta = 0.005$ ($n = 1000$)
μ_1	-0.1	-0.1 (0.04)	-0.11 (0.02)
μ_2	1.00	0.98 (0.08)	1.01 (0.06)
ω_1^2	0.04	0.04 (0.02)	0.04 (0.01)
ω_2^2	0.4	0.37 (0.15)	0.37 (0.13)
γ	4.00	4.02 (0.03)	4.00 (0.03)

$$dX_i(t) = (\Phi_{i,1}X_i(t) + \Phi_{i,2})dt + \Gamma_i^{-1/2}dW_i(t); \Gamma_i \sim G(a\lambda)$$

	value	$\Delta = 0.025$ ($n = 200$)	$\Delta = 0.005$ ($n = 1000$)
μ_1	-0.50	-0.48 (0.07)	-0.49 (0.07)
μ_2	1.00	0.97 (0.11)	0.99 (0.11)
ω_1^2	0.10	0.09 (0.06)	0.09 (0.06)
ω_2^2	0.50	0.49 (0.20)	0.52 (0.23)
m	4.00	3.96 (0.22)	4.00 (0.21)
t	1.32	1.27 (0.06)	1.31 (0.05)

Comments on these simulation results

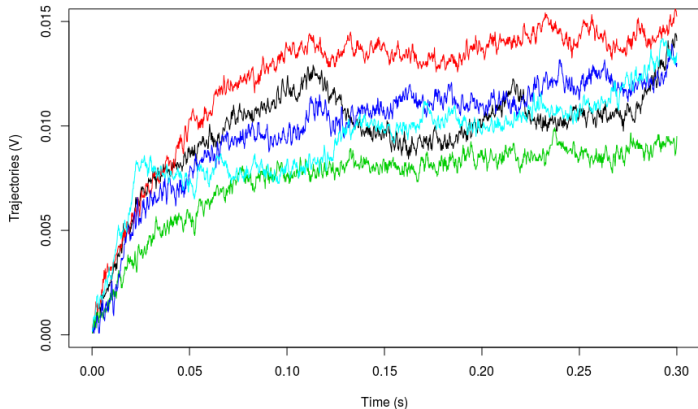
- Pb with the sets $F_{i,n}$: too stringent truncations \Rightarrow Method 2.
- Two est. methods: similar good performances (whatever n and N).
- Bias and s.d of estimates decrease as N increases.
- For N fixed, increasing n decreases the bias but no impact on the s.d . of estimates
- Agrees with theoretical results
- For $n = 200$, condition $N/n \rightarrow 0$ not fulfilled , but good results.
- Ass. (H1)(H2) not satisfied : does not deteriorate performances.
- Singular Ω (mixed effects in the drift) : parameters still well estimated

Neuronal data (from Picchini et al.,2008)

Data set: $N = 240$ membrane potential trajectories (Volts)

Observations: $n = 2000$ points on $[0, T]$ with $T = 0.3$ s

SDE MODELS: O.U.(Picchini et al, 2008,2010; Dion,2016); C.I.R (Hoepfner,2007).



Modeling neuronal data with SDE with mixed effects

$$dX_i(t) = (\Phi_{i,1}X_i(t) + \Phi_{i,2})dt + \Psi_i\sigma(X_i(t))dW_i(t), \quad X_i(0) = x_i$$

Includes $\sigma(x) \equiv 1$ (O.U.) and $\sigma(x) = \sqrt{|x|}$ (CIR).

Try to answer two questions

- Which of the OU or the CIR is the most appropriate SDE?
- Which parameter should be fixed or random?

Four models tested with $\Psi_i = \Gamma_i^{-1/2}$ with $\Gamma_i \sim G(a, \lambda)$

- 1 O.U.: $\Phi_{i,1} = \mu_1$ fixed; $\Phi_{i,2}$ random s.t. $\Phi_{i,2}|\Gamma_i \sim \mathcal{N}(\mu_2, \omega_2^2/\Gamma_i)$.
- 2 O.U.: $\Phi_{i,1}$ random s.t. $\Phi_{i,1}|\Gamma_i \sim \mathcal{N}(\mu_1, \omega_1^2/\Gamma_i)$; $\Phi_{i,2} = \mu_2$ fixed.
- 3 O.U.: $\Phi_{i,1}, \Phi_{i,2}$ random independent;
 $\Phi_{i,1}|\Gamma_i \sim \mathcal{N}(\mu_1, \omega_1^2/\Gamma_i)$, $\Phi_{i,2}|\Gamma_i \sim \mathcal{N}(\mu_2, \omega_2^2/\Gamma_i)$.
- 4 CIR: $\Phi_{i,1} = \mu_1$ fixed; $\Phi_{i,2}$ random s.t. $\Phi_{i,2}|\Gamma_i \sim \mathcal{N}(\mu_2, \omega_2^2/\Gamma_i)$.

Results

Comparison between various models comparing BIC values

$$BIC = -2 \log \hat{\mathcal{L}} + d \log N$$

- ★ $\hat{\mathcal{L}}$: likelihood of the observations evaluated at the parameter estimate
- ★ d = nb of model parameters.
- ★ Likelihood not explicit \Rightarrow use of the best approximation (Method 1)

Results

- Best model O.U. (1): $dX_i(t) = (\mu_1 X_i(t) + \Phi_{i,2})dt + \Gamma^{-1/2}dW_i(t)$
- Parameter estimates: $(\mu_1 = -0.037, \mu_2 = 0.38, \omega_2^2 = 0.015)$;
 $(a = 16.2, \lambda = 2.93)$ (corresponds to $E(\Gamma^{-1}) = 0.19$).

- ★ Consistent with previous results.
- ★ Comparison with models with fixed diffusion coefficient?
- ★ No longer possible to use BIC \Rightarrow two solutions:
- ★ Use of the Q-BIC of Eguchi & Masuda (2016) for M -estimators.
- ★ Develop rigorous testing approach (parameters located at a boundary).

Concluding remarks

- Mixed effects for stochastic differential equations on \mathbb{R} .
- Linear multidimensional mixed effect in the drift and multiplicative random effect Γ in the diff. coef. with joint distribution $\nu_\theta(., .)$.
- Discrete observations (n) of N paths observed on $[0, T]$ fixed.
- Good results over all of estimators under conditions linking N and n .
- It works well in practice even if it is not satisfied.

Extensions

- Time -dependent drift and diffusion coefficients: $b(t, x), \sigma(t, x)$: O.K.
- Assumption $X_i(0) = x$ done for simplicity $\Rightarrow X_i(0) = x_i$ is O.K.
- Multidimensional mixed effects diffusion models on \mathbb{R}^k :
$$dX_i(t) = B(X_i(t))\Phi_i dt + \Psi_i \Sigma(X_i(t)) dW_i(t); X_i(0) = x.$$
- Adding fixed unknown parameters in b, σ : $b(\alpha, x), \sigma(\beta, x)$?
- Testing methods to decide which parameters are fixed or random?

THANKS FOR YOUR ATTENTION !

General References

- Nie & Yang (2005), Nie (2006, 2007). Theoretical likelihood study. Rely on many abstract assumptions impossible to check in practice.
- Donnet, S. & Samson, A. (2008). Review for mixed effects SDEs.
- Picchini, De Gaetano & Ditlevsen (2008, 2010); Picchini & Ditlevsen (2011) (approximations of the likelihood, no theoretical results)
- Delattre, Genon-Catalot & Samson (2012, 2015, 2016); Genon-Catalot & Larédo (2016); **Delattre, Genon-Catalot & Larédo (Preprints 2016, 2017) (parametric, likelihood methods).**
- Comte, Genon-Catalot & Samson (2013), Genon-Catalot & Dion (2015) (non parametric)
- Große Ruse, Samson & Ditlevsen (Preprint 2017) (Multidimensional diff., Mixed effects in the drift+ covariates.)

References on applications based on data sets of PK/PD dynamics

- Overgaard, Jonsson, Tornøe & Madsen (2005)
- Berglund, Sunnake, Adiels, Jirstrand & Wennberg (2011)
- Leander, J., Almquist, J., Ahlstrom, C., Gabrielsson, J. & Jirstrand, M. (2015) (concrete models and real data + many references therein)